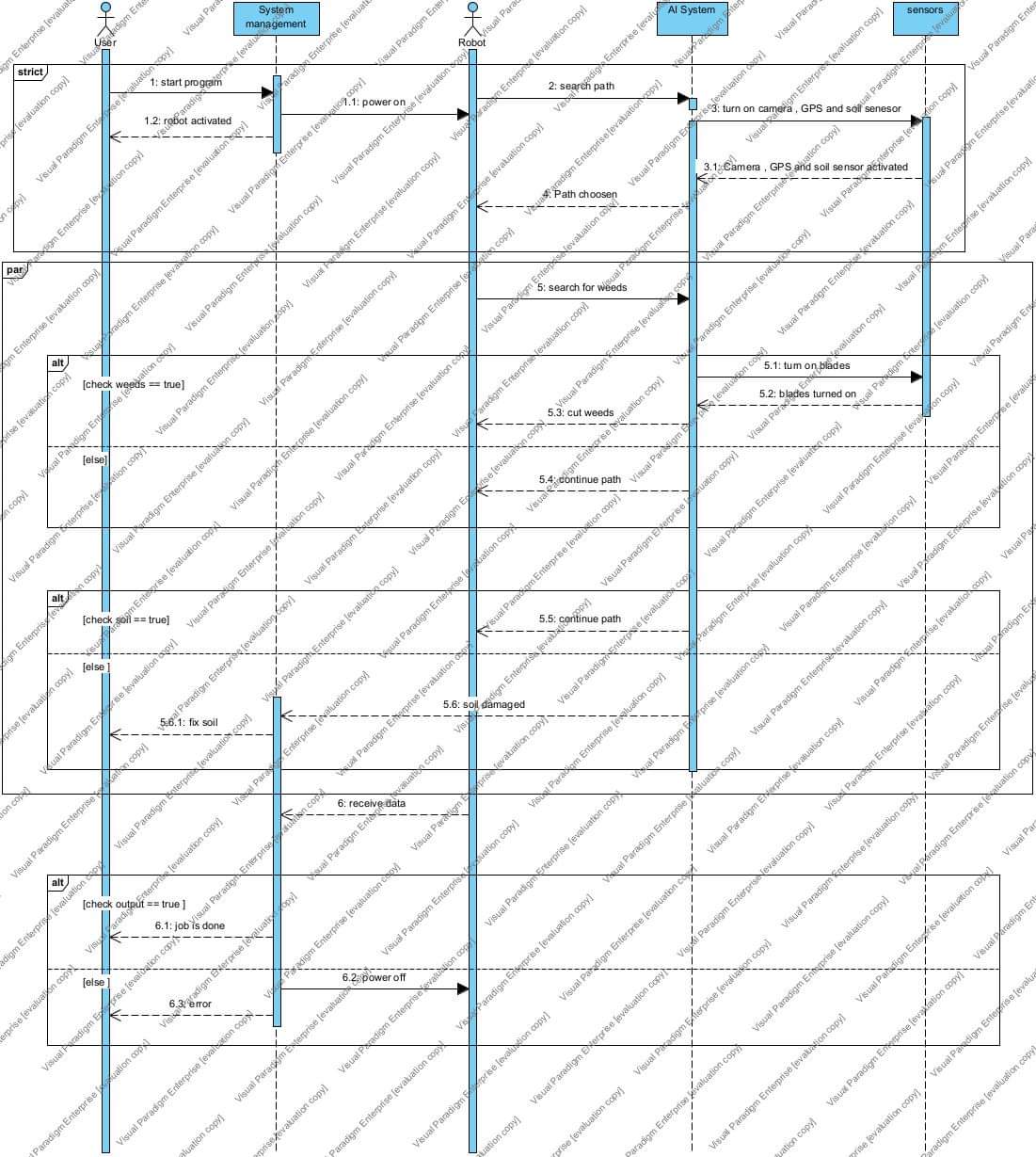
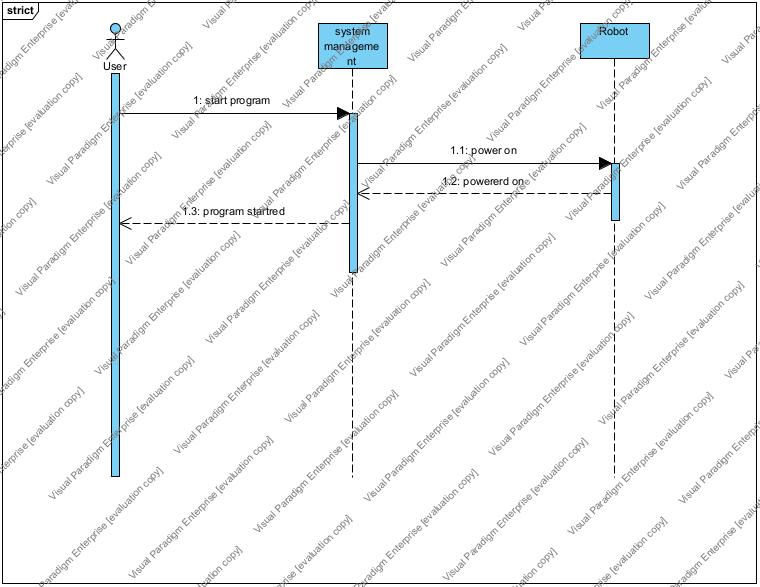
Phase one

Robot weeding project

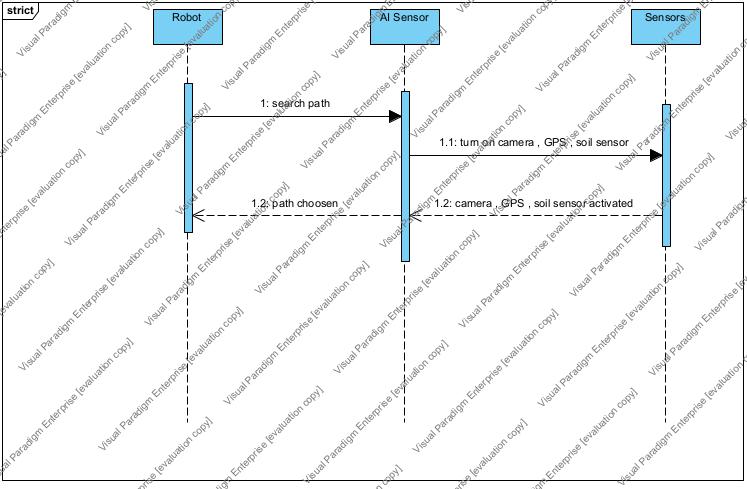
Sequence diagram

Sequence diagram #1

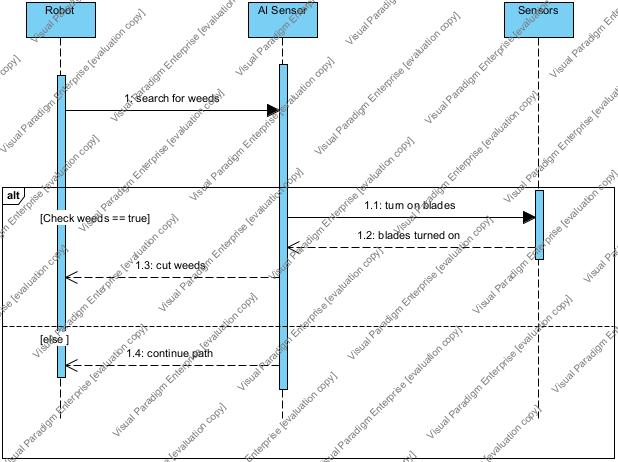
Start program:

Sequence diagram #2

The appropriate path:

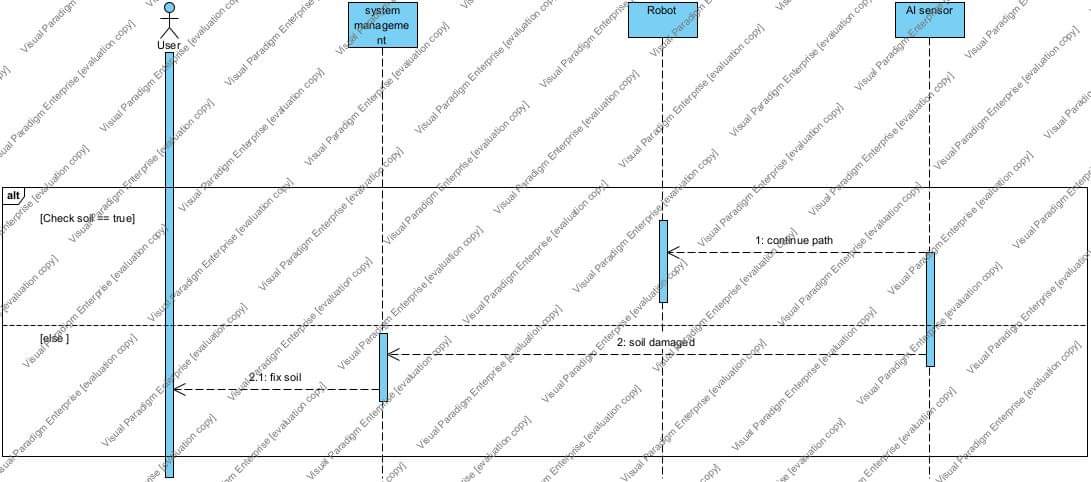


Sequence diagram #3

Detection of weeds:

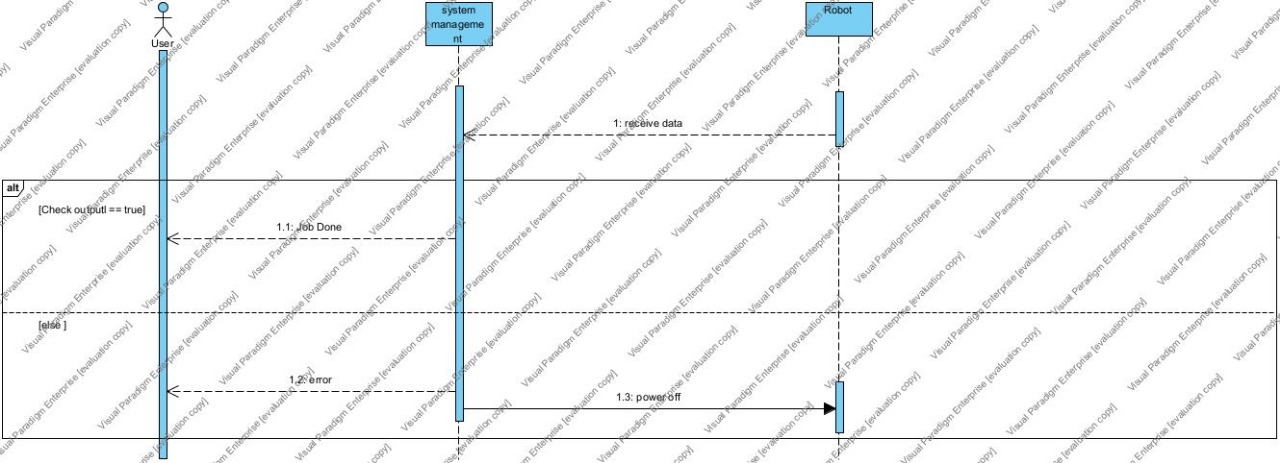
Sequence diagram #4

Soil analysis:

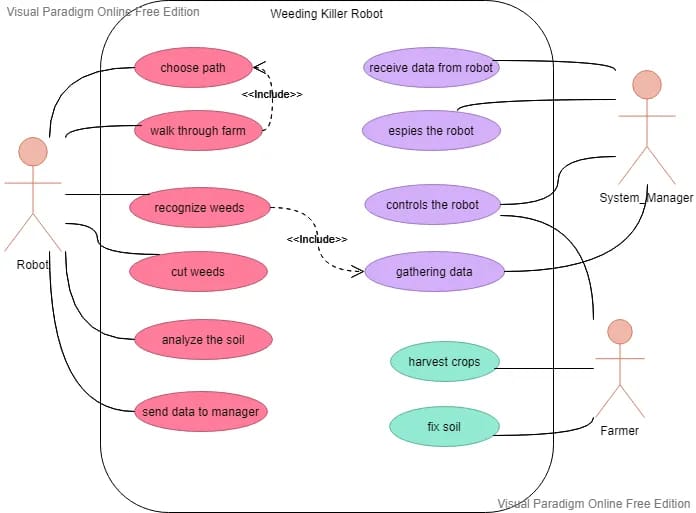


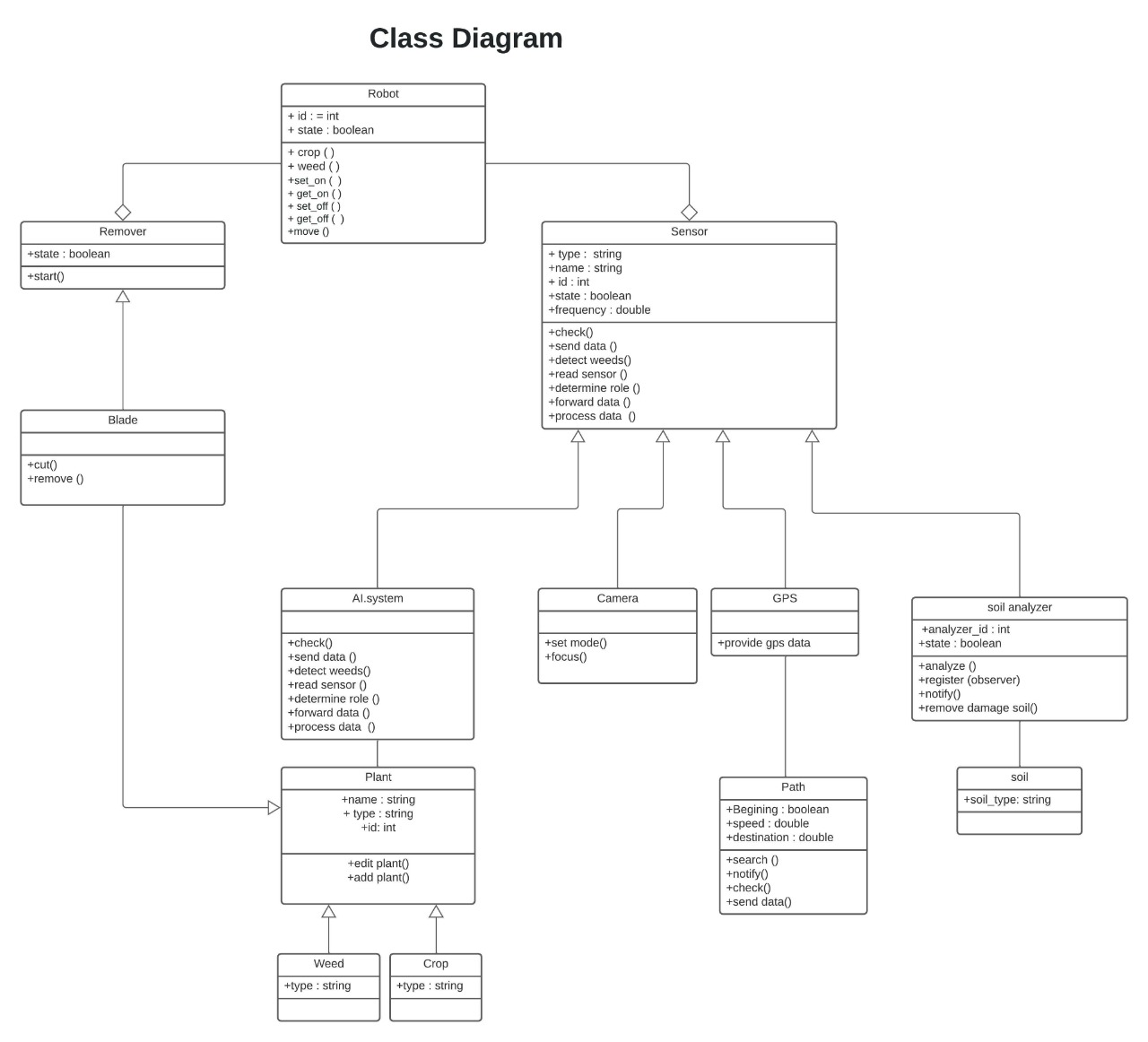
Sequence diagram #5

Receive data:

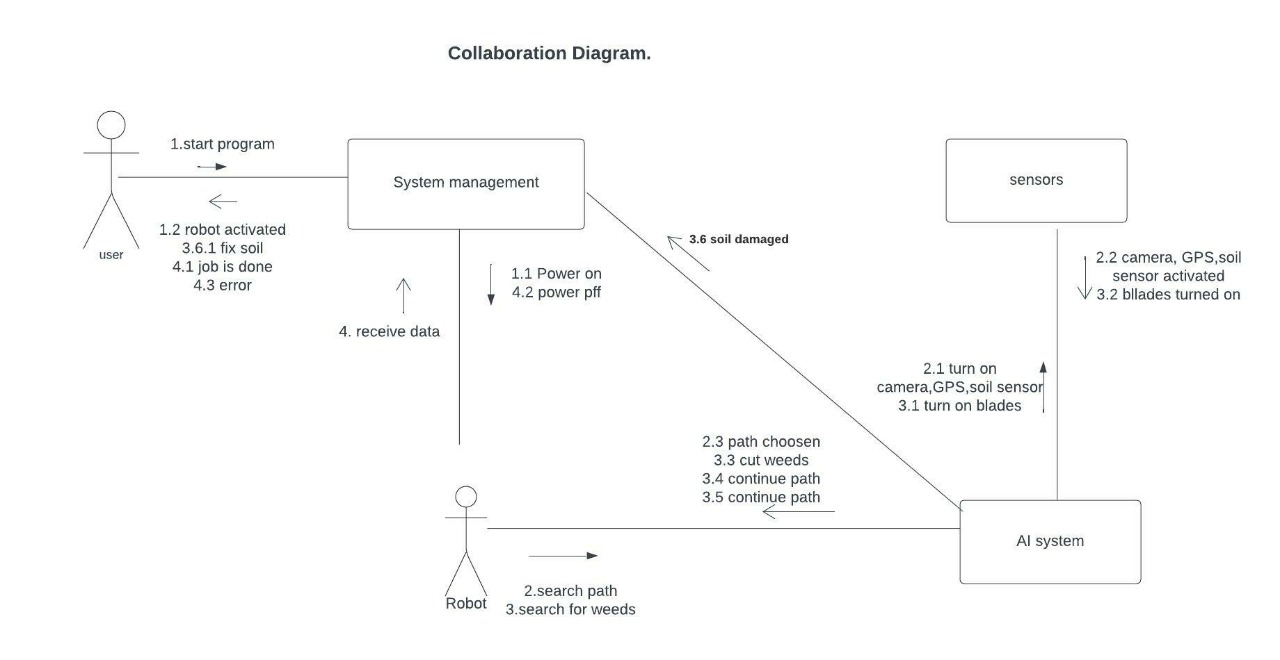


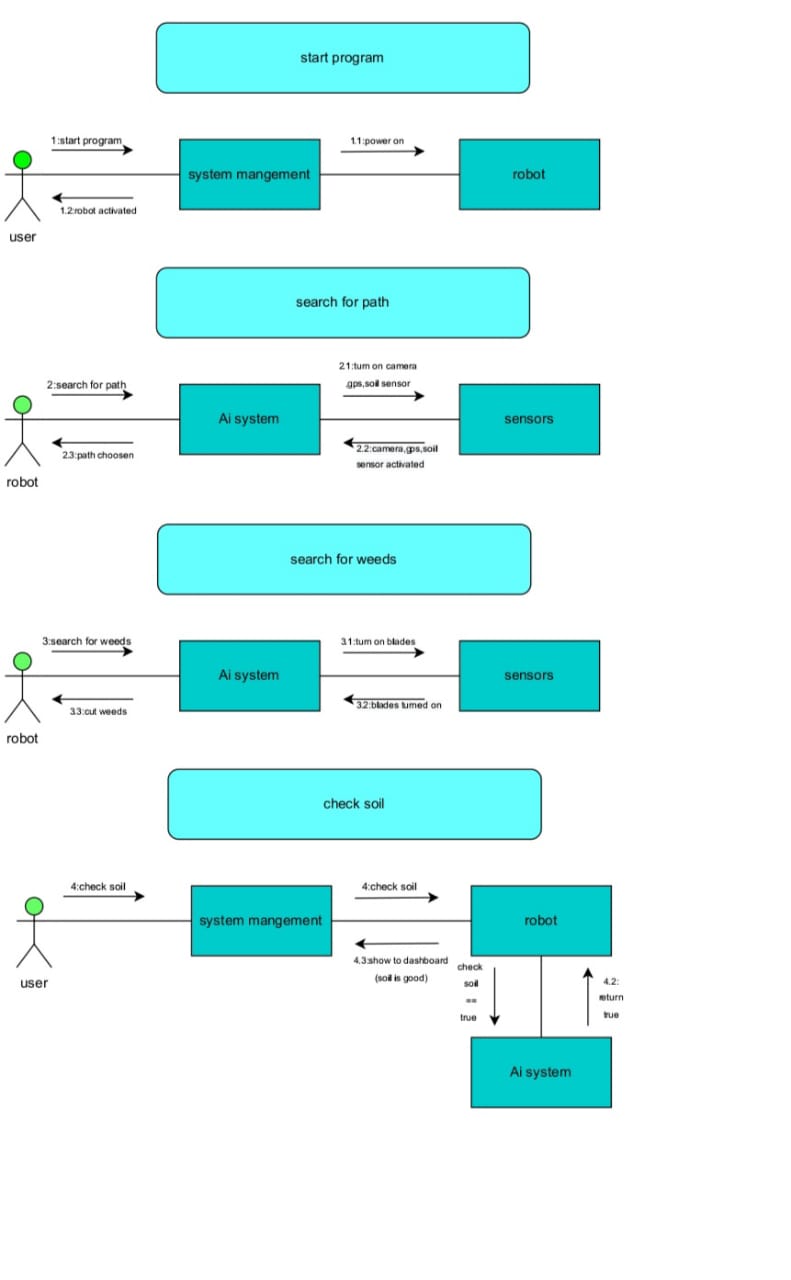
Use case diagram

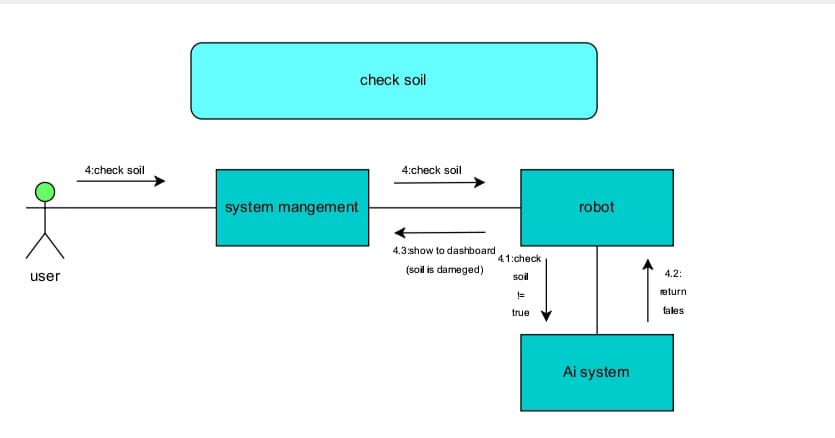


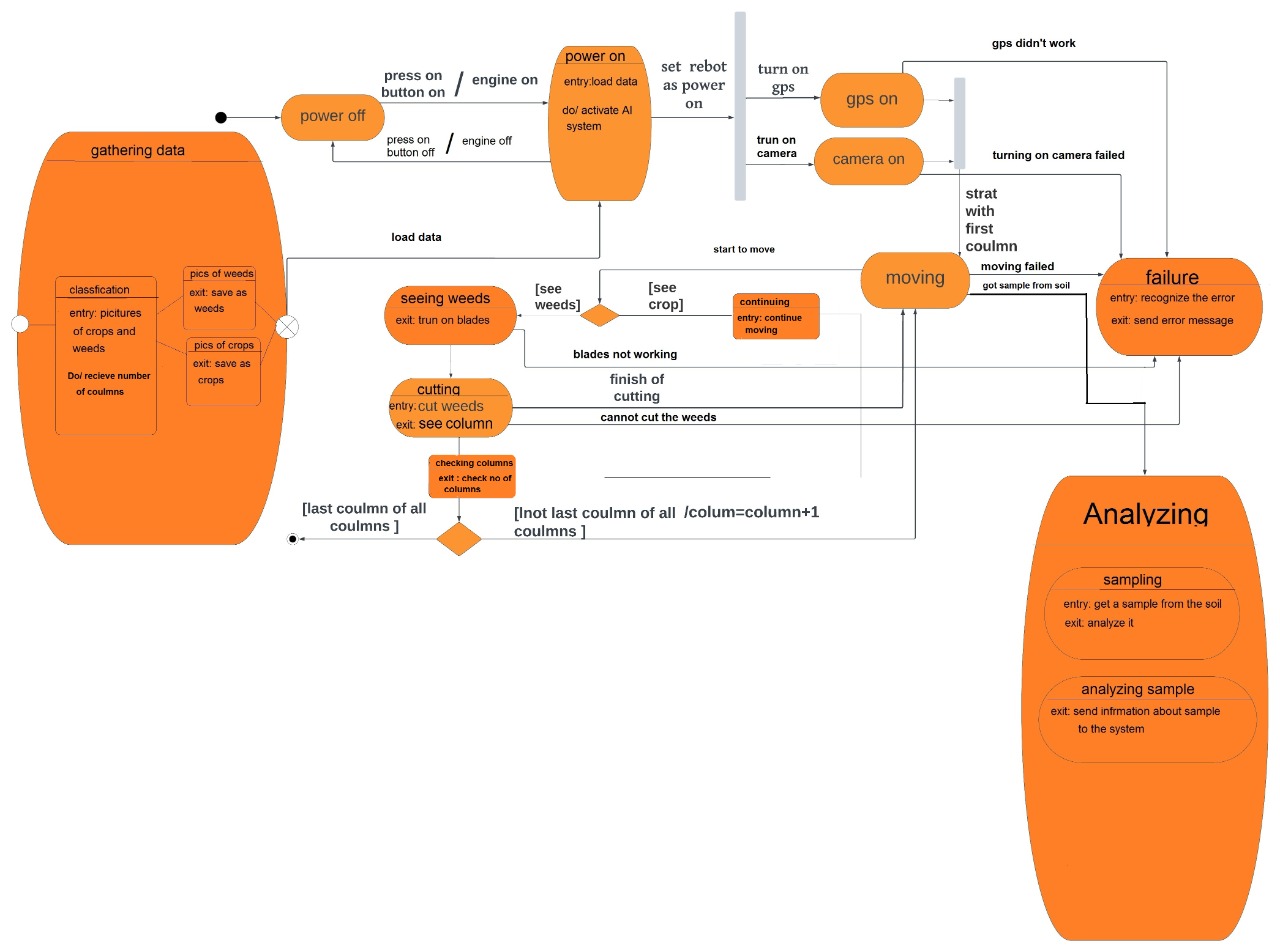
Class diagram

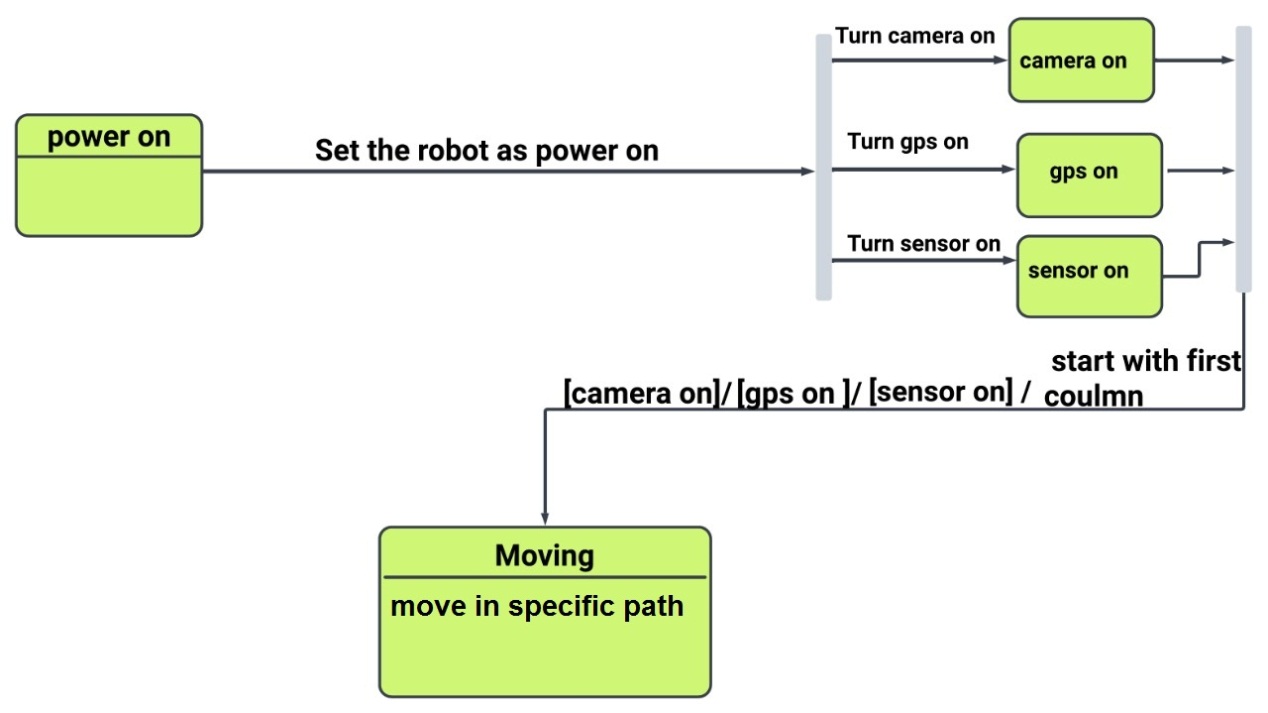
Collaboration diagram #1

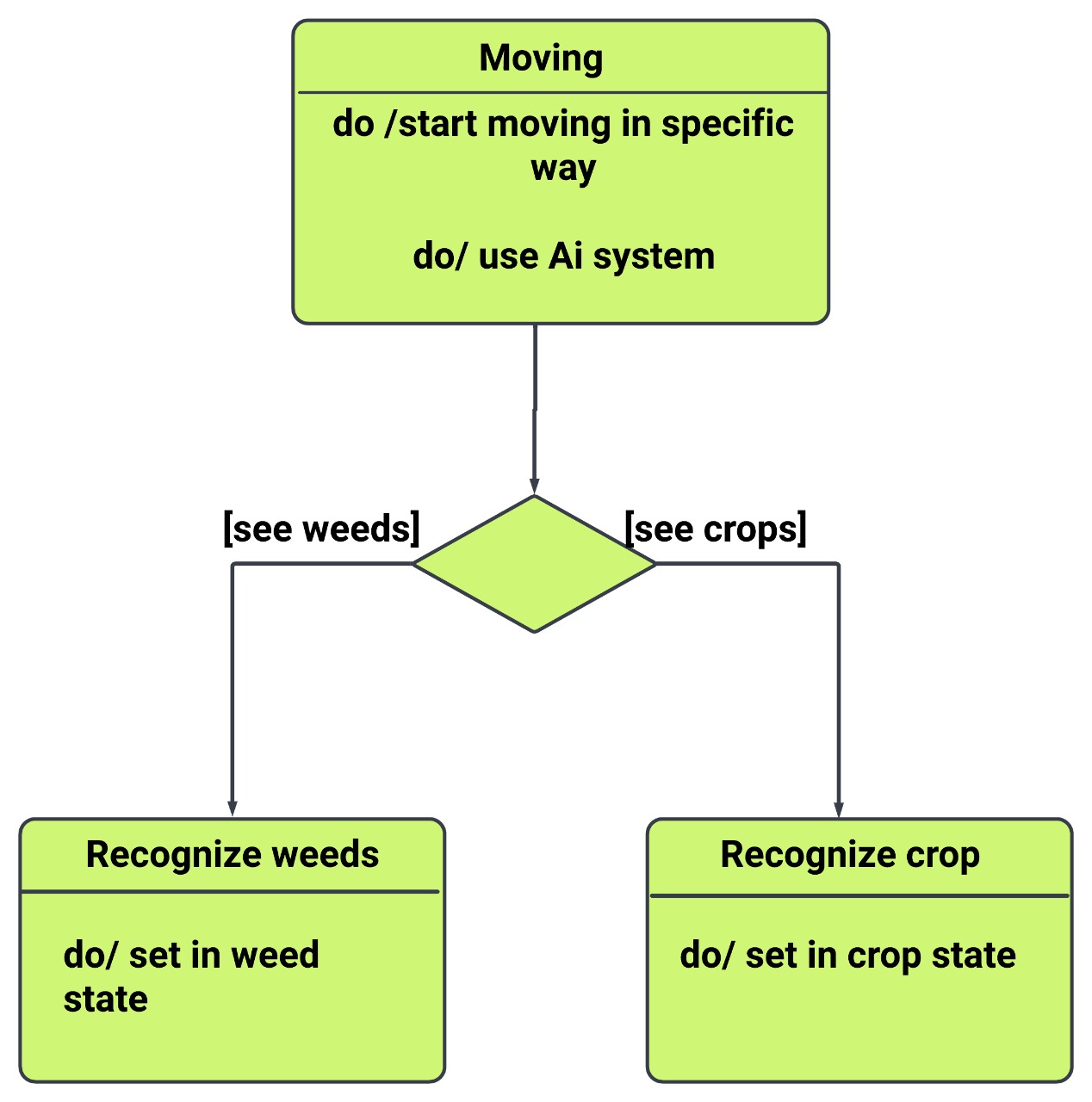


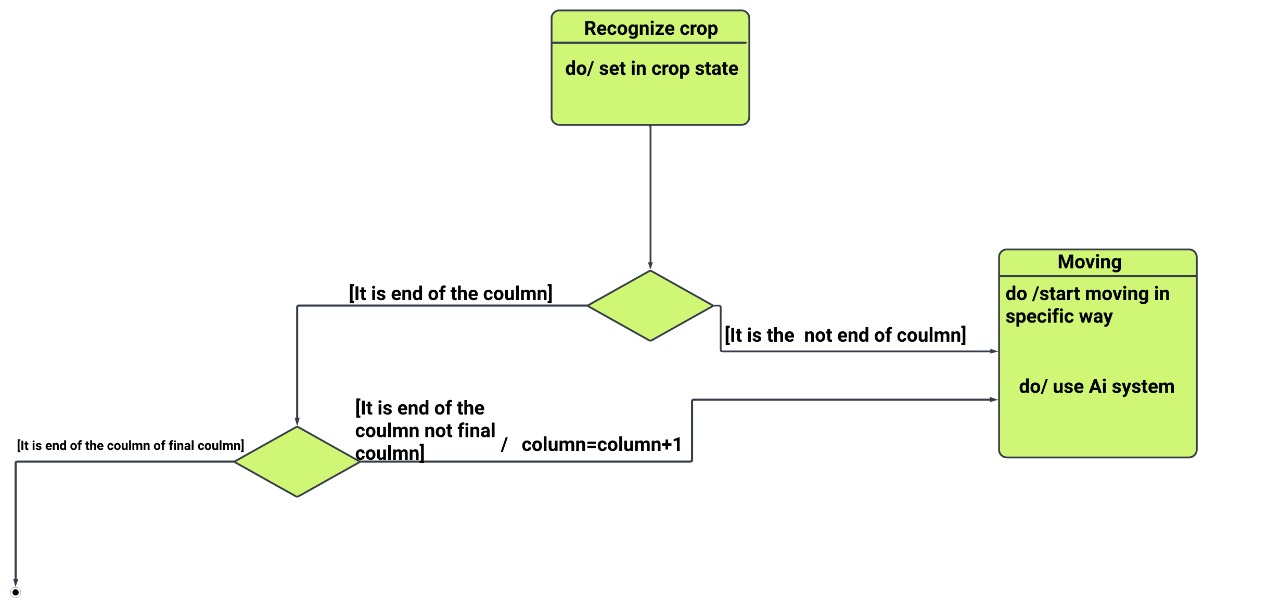
Collaboration diagram #2

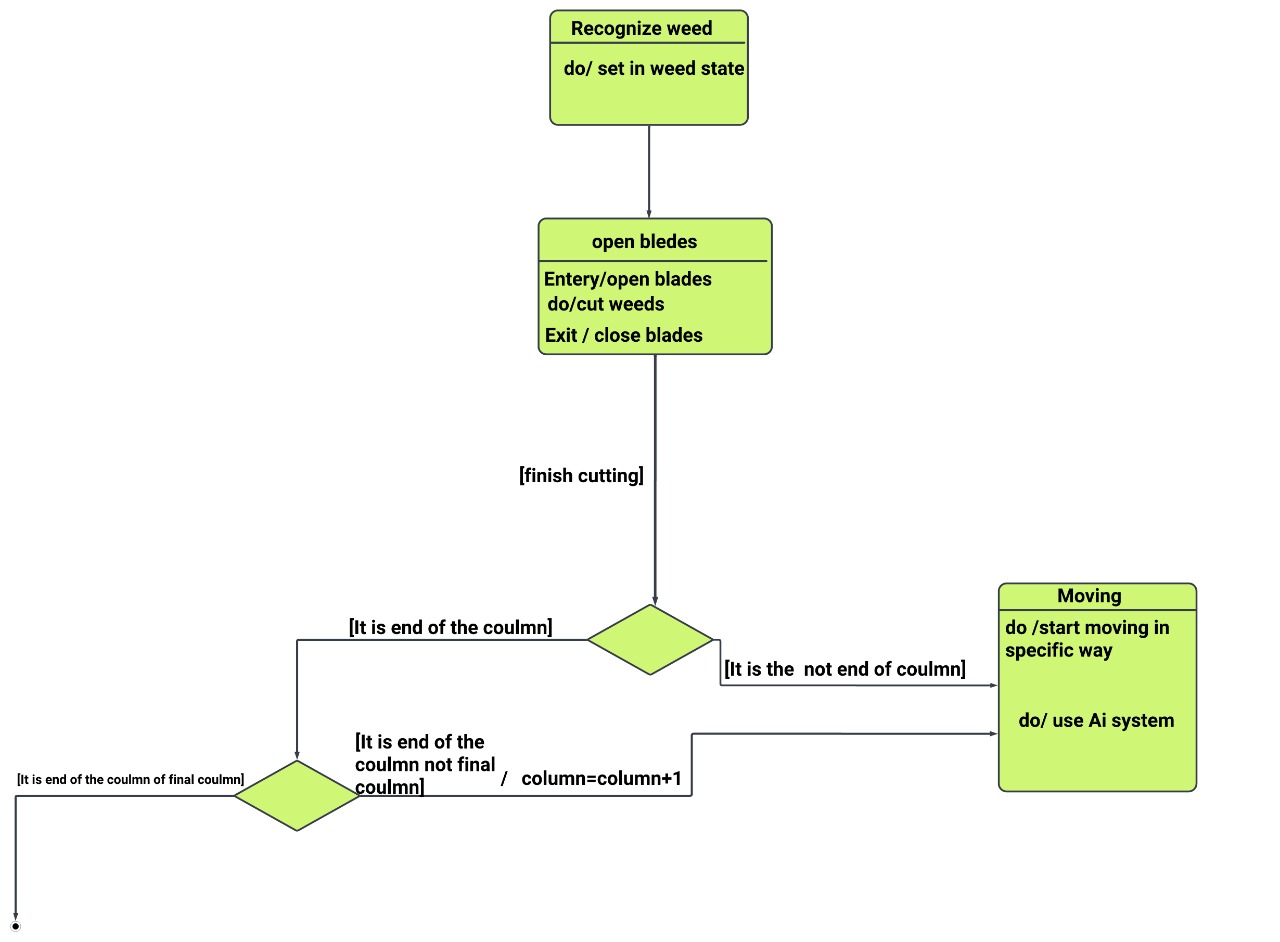


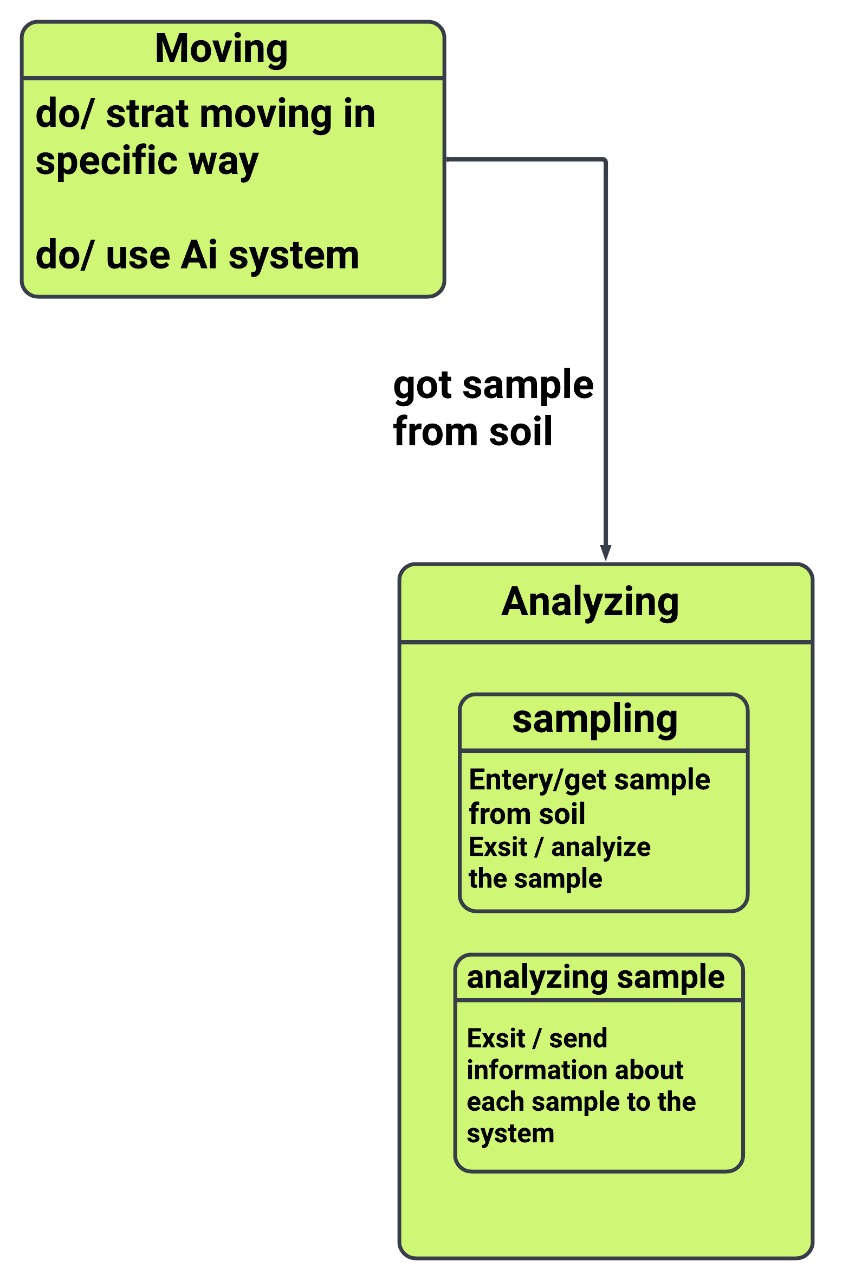
State machine diagram

State machine #1

State machine #2

State machine #3

State machine #4

State machine #5